

# Introduction to Job Submission on Summit

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# Jsrun is the job launcher for Summit



# bsub -Submit a Job to LSF



 bsub allocates 1 batch node plus the number of requested compute nodes.

bsub -alloc\_flags defines allocation-wide configurations

- Applied to every compute node
  - CPU Simultaneous Multithreading Level (smt)
  - <u>GPU Multi-Process Service</u> (gpumps)
  - Burst Buffer (nvme)
  - Others (spectral, maximizegpfs,...)
- Multiple options require quoting, space separated
  - #BSUB -alloc\_flags "gpumps smt1 nvme"

# Jsrun is the job launcher for Summit



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# Summit Node

- IBM Power System AC922
  Compute Node
- 2 Sockets
  - 3 NVIDIA V100 GPUs
  - 21 usable cores
    - {1, 2, 4}-way Multithreading (SMT)
  - 256 GB DDR4 RAM
- 1.6 TB NVMe (Burst Buffer)
- Exclusive access during job
- X-bus(64GB/s)



#### NVMe 1.6 TB



### **Resource Sets**

jsrun [-n #resource sets] [tasks, threads, and GPUs in each resource set] program [program args]

Socket 0 Socket 1 X-bus  $\leftrightarrow$ Memory Memory (256GB) (256GB)

jsrun -n6 -c7 -a1, -g1 ./a.out

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### **Resource Sets**

jsrun [-n #resource sets] [tasks, threads, and GPUs in each resource set] program [program args]

- Used to shape the compute node to your application by grouping
  - Physical cores
  - GPUs
  - RAM
- Must contain 1 or more physical cores and 0 or more GPUs
- Allow for <u>multiple job steps on a</u> <u>single node (Adv.)</u>
- Highly flexible with <u>Explicit Resource</u> <u>Files (Adv.)</u>
- Not as scary as they seem



jsrun -n6 -c7 -a1, -g1 ./a.out

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### **Resource Sets**

jsrun [-n #resource sets] [tasks, threads, and GPUs in each resource set] program [program args]

### Some limitations

- A resource set may span sockets, but *cannot* span nodes
  - Creating resource sets within sockets can avoid cross-socket communication
- Memory access requires a physical core or GPU on its host socket
- Resource Sets are homogeneous by default
  - Heterogeneous resourcesets possible with ERF (Adv.)



### Designing a Resource Set

jsrun [-n #resource sets] [tasks, threads, and GPUs in each resource set] program [program args]

Flags			
Long	Short	Description	Default Value
nrs	-n	Number of resource sets	All available physical cores
tasks_per_rs	-a	Number of MPI tasks (ranks) per resource set	Not set by default, instead total tasks (-p) set
cpu_per_rs	-c	Number of CPUs (cores) per resource set.	1
gpu_per_rs	-g	Number of GPUs per resource set	0
bind	-b	Binding of tasks within a resource set. Can be none, rs, or packed:#	packed:1
rs_per_host	-r	Number of resource sets per host	No default
latency_priority	-1	Latency Priority. Controls layout priorities. Can currently be cpu-cpu or gpu-cpu	gpu-cpu,cpu-mem,cpu-cpu
launch_distribution	-d	How tasks are started on resource sets	packed

# Designing a Resource Set

jsrun [-n #resource sets] [tasks, threads, and GPUs in each resource set] program [program args]

- 1. Understand how the code expects the node to appear
  - How many tasks/threads per GPU?
  - Does each task expect to see a single GPU?
  - Do multiple tasks expect to share a GPU (gpumps)?
  - Is the code written to internally manage task to GPU workloads based on the number of available cores and GPUs?
- 2. Create Resource Sets containing the needed GPU to task binding
  - Describe a resource set that meets the requirements above. If the code is written for one GPU per task, consider a resource set with just one GPU
- 3. Decide on the number of Resource Sets needed
  - After understanding task, thread, and GPU requirements, scale the number of Resource Sets (and number of nodes) as needed.



### Examples

#### jsrun -n1

- By default you get one core with one task.
- This is the same as

#### jsrun -n1 -c1 -a1

• Better not to rely on defaults

Let's add a GPU . . .

Socket 0													Socket 1
							3						
	_	_											
	0												Memory (256GB)
	002	003											
						X-bus							
Memory	012						100						
(256GB)													
	024												
disabled						NVMe (1.6TB)							



### Examples

#### jsrun -n1 -c1 -a1 -<u>g1</u>

- -g flag specifies the number of GPUs per resource set.
- How many of these sets can we fit on the node?

Socket 0							Socket 1
	0	1		3			
	0 001	028 029		088			
	002 003	030 031		090			L II
				092			L II
				094			L II
				096			L II
			X-bus	098			L II
Memory				100			Memory
(256GB)			071 102 103 130		(256GB)		
				104			L II
				106			L II
				108			L II
				110			L II
				112			L II
				114			
disabled			NVMe (1.6TB)				



.

### Examples

jsrun <u>-n6</u> -c1 -a1 -g1

• How would this scale to two or more nodes?

Socket 0	cket 0													Socket 1
	0		1			2		3		4		5		
	0	001	028	029	056	057		3	089			144	145	
	002	003						090	091					
	1	005						4	093					
	006	007						094	095					
	2	009						5	097					
Memory (256GB)	010	011					X-bus	098	099					
	012	013						100						Memory (256GB)
sahled														



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## Examples: Multiple Nodes

#### jsrun <u>-n12</u>-c1 -a1 -g1

- -n will be the number of nodes you reserved multiplied by the number of resource sets on one node.
- If your resources sets don't fill both sockets, jsrun may not map the resources set as you expect when you expand to multiple nodes.
- Let's talk about that and threads next.



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# Examples : Threading

#### jsrun -n1 -c7 -a1 <u>-EOMP\_NUM\_THREADS=7</u> -g1

- -EOMP\_NUM\_THREADS=# lets you set the number of openMP threads per task.
- Could also do export OMP\_NUM\_THREADS=7 just before the jsrun command.
- All 7 threads are clustered on the same core!
- How do we fix this?



# Examples: Threading -brs

#### jsrun -n1 -c7 -a1 -EOMP\_NUM\_THREADS=7 -g1 <u>-brs</u>

- -b controls the thread binding options are packed:#, rs, none
- allows you to set the number of physical cores available to an MPI task
- -b rs binds the threads to fill the available cores. In the resource set
- How would I do this over 2 nodes?



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## Examples: Threading multiple nodes

jsrun <u>-n2</u>c7 -a1 -EOMP\_NUM\_THREADS=7 -g1 -brs





**!Wast of Allocation!** 

# Examples: Threading multiple nodes

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Remember you must have a core or GPU reserved on each socket to get access to that socket's CARCHING LEADERSH MEMORY, SO what you see above does not give each resource set 512 GB, but rather only 265 GB.

# Examples: Threading multiple nodes

#### jsrun -n2 --rs\_per\_socket 1 -c7 -a1 -EOMP\_NUM\_THREADS=7 -g1 -brs

- Setting the resource sets per socket to 1 gives you one set on each socket, each able to get full access to that node's 265 GB of RAM.
- This gives you a more efficient use of allocation than the configuration on the previous slide.

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If you used -n 4, you'd get two nodes that look like this.

### Resources

- OLCF user docs for running jobs:
  - https://docs.olcf.ornl.gov/systems/summit\_user\_guide.html#running-jobs
    - Covers main jsrun options with examples of each.
    - Also options for monitoring your jobs.
- man jsrun
  - This has the complete descriptions of all Jsrun options and advice about how combinations of those options will be interpreted
- Job-step-viewer
  - Demo: <u>https://jobstepviewer.olcf.ornl.gov</u>
  - How To: <u>https://docs.olcf.ornl.gov/systems/summit\_user\_guide.html#job-step-viewer</u>
- New User Quick Start guide: <u>https://docs.olcf.ornl.gov/quickstart/index.html</u>
  - Has slides and recordings of past jsrun trainings (and many other new user topics)
  - Hands on exercises with answers for jsrun







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### New User Quick Start

Direct your browser to https://docs.olcf.ornl.gov/quickstart/index.html

Login to summit.

\$ ssh vour\_user\_name@summit.olcf.ornl.gov

(PIN followed by your RSA token code.)

- git clone <u>https://github.com/olcf/NewUserQuickStart.git</u>
  - cd NewUserQuickStart
- Do Basic Workflow to learn about Batch scripts and job submission
  - \$ cd hands-on/Basic\_Workflow/
- Do Jsrun basics to practice what you have learned in this lecture.
  - cd hands-on/jsrun\_Job\_Launcher/

I'll go to the repo now and walk you through the exercises . . .

